

Contribution



- A novel approach for the **photo enhancement task** based on learning a mapping function between photos from mobile devices and a DSLR camera.
- A new large-scale **DPED dataset** consisting of over 22K photos taken synchronously by a DSLR camera and 3 low-end cameras of smartphones.
- Experiments measuring objective and subjective quality demonstrating the advantage of the enhanced photos over the originals and, at the same time, their comparable quality with the DSLR counterparts.

Proposed Photo Enhancer



to reproduce the image I_t (target image) taken by a DSLR generator objective (F_W and D – generator and discrimicamera. A deep residual CNN F_{W} is used to learn this nator): translation function, and is trained to minimize a loss function consisting of the following terms:

• **Color loss:** To measure the color difference between the enhanced and target images, we propose applying a Gaussian blur and computing Euclidean distance between the obtained representations:

$$\mathcal{L}_{\text{color}}(X,Y) = \|X_b - Y_b\|_2^2,$$

where X_b and Y_b are the blurred images X and Y.

• **Texture loss:** We build upon GANs to learn a suitable metric for measuring texture quality. The discriminator CNN observes fake (improved) and real (target) grayscale images, and its goal is to predict whether the input image is real or not. It is trained to minimize the cross-entropy

Given a low-quality photo I_s (source image), the goal is loss function, and the texture loss is defined as a standard

$$\mathcal{L}_{\text{texture}} = -\sum_{i} \mathbf{l}_{i}$$

where $F_{\mathbf{W}}$ and D – generator and discriminator nets.

pre-trained VGG-19 network:

$$\mathcal{L}_{\text{content}} = \alpha \| \psi_j (F$$

• Final loss: The final loss is defined as a weighted sum of previous losses with the following coefficients:

$$\mathcal{L}_{\text{total}} = \mathcal{L}_{\text{content}} + 0.4 \cdot \mathcal{L}_{\text{text}}$$

DSLR-Quality Photos on Mobile Devices with Deep Convolutional Networks

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Proposed DPED Dataset



DPED dataset consists of photos taken in the wild synchronously by three smartphones and one DSLR camera. The devices were mounted on a tripod and activated remotely by a wireless control system. The photos were captured in automatic mode during the daytime in a wide variety of places and in various illumination and weather conditions.

Experiments

We quantitatively compare Apple Photo Enhancer (APE), Dong et al., Johnson et al., and our method on the considered task. First, one can note that our method is the best in terms of SSIM, at the same time producing images that are cleaner and sharper, thus perceptually performs the best. On PSNR terms, our method competes with the state of the art: it slightly improves or worsens depending on the dataset, i.e., on the actual phone used: alignment issues could be responsible for these minor variations.

Phone	APE		Dong et al.		Johnson et al.		Ours	
	PSNR	SSIM	PSNR	SSIM	PSNR	SSIM	PSNR	SSIM
iPhone	17.28	0.8631	19.27	0.8992	20.32	0.9161	20.08	0.9201
BlackBerry	18.91	0.8922	18.89			0.9298	20.07	0.9328
Sony	19.45	0.9168	21.21	0.9382	21.33	0.9434	21.81	0.9437



From left to right, top to bottom: original iPhone photo and the same image after applying, respectively: APE, Dong et al., Johnson et al., our generator network, and the corresponding DSLR image.

User Study

To measure overall quality we designed a no-reference user study where subjects are repeatedly asked to choose the better looking picture out of a displayed pair. The results indicate that in all cases both pictures taken with a DSLR as well as pictures enhanced by the proposed CNN are picked much more often than the original ones taken with the mobile devices. When subjects are asked to select the better picture among the DSLR-picture and our enhanced picture, the choice is almost random. This means that the quality difference is inexistent or indistinguishable, and users resort to chance.

Acknowledgements

The work is supported by the ETH Zurich General Fund (OK), Toyota via the project TRACE-Zurich, the ERC grant VarCity, and an NVidia GPU grant.

 $\log D(F_{\mathbf{W}}(I_s), I_t).$

• Content loss: We define our content loss based on the activation maps $\psi_i()$ produced by the ReLU layers of the

 $F_{\mathbf{W}}(I_s)) - \psi_j(I_t) \|.$

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\mathcal{L}_{ture} + 0.1 \cdot \mathcal{L}_{color} + 400 \cdot \mathcal{L}_{tv}
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dped-photos.vision.ee.ethz.ch

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Camera	
iPhone 3GS	
BlackBerry Passport	
Sony Xperia Z	
Canon 70D DSLR	

Sensor Photo quality 3 MP Poor 13 MP Mediocre 13 MP Average 20 MP Excellent



Visual Results



iPhone 3GS

Limitations

Two typical artifacts that can appear on the processed images are color deviations and high contrast levels. Although they often cause rather plausible visual effects, in some situations this can lead to content changes that may look artificial, i.e. greenish asphalt in the second image. Another notable problem is noise amplification – due to the nature of GANs, they can effectively restore high frequency-components. However, high-frequency noise is emphasized too. Note that this noise issue occurs mostly on the lowest-quality photos (i.e., iPhone), not on the better phone cameras.



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